

# T H Lee

## List of Publications by Year in Descending Order

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The third column is the impact factor (IF) of the journal, and the fourth column is the number of citations of the article.

35  
papers

868  
citations

16  
h-index

29  
g-index

44  
ext. papers

1,026  
ext. citations

2.9  
avg, IF

3.46  
L-index

#	Paper	IF	Citations
35	Classification of self-paced finger movements with EEG signals using neural network and evolutionary approaches <b>2009</b> ,		4
34	Robust adaptive control for a class of uncertain strict-feedback nonlinear systems. <i>International Journal of Robust and Nonlinear Control</i> , <b>2009</b> , 19, 746-767	3.6	40
33	Facial expression recognition and tracking for intelligent human-robot interaction. <i>Intelligent Service Robotics</i> , <b>2008</b> , 1, 143-157	2.6	18
32	Adaptive Neural Networks Control for a Class of Pure-feedback Systems in Discrete-time <b>2007</b> ,		3
31	Automated Fault Detection and Diagnosis in Mechanical Systems. <i>IEEE Transactions on Systems, Man and Cybernetics, Part C: Applications and Reviews</i> , <b>2007</b> , 37, 1360-1364		25
30	A Stability Criterion for Arbitrarily Switched Second Order LTI Systems <b>2007</b> ,		6
29	Adaptive Predictive Control of a Class of Strict-feedback Discrete-time Systems using Discrete Nussbaum Gain. <i>Proceedings of the American Control Conference</i> , <b>2007</b> ,	1.2	2
28	Output feedback NN control of NARMA systems using discrete Nussbaum gain <b>2007</b> ,		2
27	Adaptive Smart Neural Network Tracking Control of Wheeled Mobile Robots <b>2006</b> ,		5
26	Hand Gesture Recognition and Tracking based on Distributed Locally Linear Embedding <b>2006</b> ,		4
25	A Study on Distribution Preservation Mechanism in Evolutionary Multi-Objective Optimization. <i>Artificial Intelligence Review</i> , <b>2005</b> , 23, 31-33	9.7	32
24	Evolutionary computing for knowledge discovery in medical diagnosis. <i>Artificial Intelligence in Medicine</i> , <b>2003</b> , 27, 129-54	7.4	100
23	Adaptive NN control for a class of discrete-time non-linear systems. <i>International Journal of Control</i> , <b>2003</b> , 76, 334-354	1.5	82
22	Automating the drug scheduling of cancer chemotherapy via evolutionary computation. <i>Artificial Intelligence in Medicine</i> , <b>2002</b> , 25, 169-85	7.4	46
21	Learning the Search Range for Evolutionary Optimization in Dynamic Environments. <i>Knowledge and Information Systems</i> , <b>2002</b> , 4, 228-255	2.4	3
20	Variable structure control of a distributed-parameter flexible beam. <i>Journal of Field Robotics</i> , <b>2001</b> , 18, 17-27		37
19	Adaptive robust stabilization of dynamic nonholonomic chained systems. <i>Journal of Field Robotics</i> , <b>2001</b> , 18, 119-133		23

18	Adaptive-Predictive Control of a Class of SISO Nonlinear Systems. <i>Journal of Dynamical and Control Systems</i> , <b>2001</b> , 11, 151-174		50
17	A multiobjective evolutionary algorithm toolbox for computer-aided multiobjective optimization. <i>IEEE Transactions on Systems, Man, and Cybernetics</i> , <b>2001</b> , 31, 537-56		44
16	ADAPTIVE BACKSTEPPING CONTROL OF A CLASS OF CHAOTIC SYSTEMS. <i>International Journal of Bifurcation and Chaos in Applied Sciences and Engineering</i> , <b>2000</b> , 10, 1149-1156	2	89
15	Generalized Predictive Observer-Controller For Injection Moulding. <i>International Polymer Processing</i> , <b>1999</b> , 14, 399-408	1	3
14	Rule-based control of Wiener-type nonlinear processes through self-organizing. <i>International Journal of Systems Science</i> , <b>1998</b> , 29, 275-286	2.3	2
13	Adaptive neural network control of flexible joint robots based on feedback linearization. <i>International Journal of Systems Science</i> , <b>1998</b> , 29, 623-635	2.3	11
12	Real-time neural-network-based control of a gyro-mirror line-of-sight stabilization platform. <i>International Journal of Systems Science</i> , <b>1998</b> , 29, 745-758	2.3	0
11	Dynamic Modeling of a Smart Materials Robot. <i>AIAA Journal</i> , <b>1998</b> , 36, 1466-1478	2.1	26
10	A nonlinear feedback controller for a single-link flexible manipulator based on a finite element model. <i>Journal of Field Robotics</i> , <b>1997</b> , 14, 165-178		52
9	Tip Tracking Control of a Single-Link Flexible Robot: A Backstepping Approach. <i>Journal of Dynamical and Control Systems</i> , <b>1997</b> , 7, 341-360		8
8	A model-based adaptive sliding controller. <i>International Journal of Systems Science</i> , <b>1996</b> , 27, 129-140	2.3	10
7	Robust Smith-predictor controller for uncertain delay systems. <i>AIChE Journal</i> , <b>1996</b> , 42, 1033-1040	3.6	45
6	Enhanced automatic tuning procedure for process control of PI/PID controllers. <i>AIChE Journal</i> , <b>1996</b> , 42, 2555-2562	3.6	75
5	Robust control of robot manipulators with fast load adaptation. <i>International Journal of Systems Science</i> , <b>1995</b> , 26, 1539-1548	2.3	
4	A Knowledge-based approach to dead-time estimation for process control. <i>International Journal of Control</i> , <b>1995</b> , 61, 1045-1072	1.5	4
3	Parallel Adaptive Neural Network Control of Robots. <i>Proceedings of the Institution of Mechanical Engineers Part I: Journal of Systems and Control Engineering</i> , <b>1994</b> , 208, 231-237	1	2
2	Adaptive modal parameters identification for collocated position feedback vibration control. <i>International Journal of Control</i> , <b>1991</b> , 53, 597-617	1.5	8
1	Extended Generalised Predictive Control incorporating Feedforward <b>1990</b> ,		4

