Yue Zhao

List of Publications by Year in descending order

Source: https://exaly.com/author-pdf/10577054/publications.pdf

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10	160	7	9
papers	citations	h-index	g-index
10	10	10	124
all docs	docs citations	times ranked	citing authors

#	Article	IF	Citations
1	Mechanism design and workspace analysis of a hexapod robot. Mechanism and Machine Theory, 2022, 174, 104917.	4.5	12
2	Terrain classification and adaptive locomotion for a hexapod robot Qingzhui. Frontiers of Mechanical Engineering, 2021, 16, 271-284.	4.3	15
3	A real-time low-computation cost human-following framework in outdoor environment for legged robots. Robotics and Autonomous Systems, 2021, 146, 103899.	5.1	6
4	Staircase-climbing capability-based dimension design of a hexapod robot. Mechanism and Machine Theory, 2021, 164, 104400.	4.5	10
5	Stair Climbing Capability-Based Dimensional Synthesis for the Multi-legged Robot. , 2021, , .		3
6	Novel method of gait switching in six-legged robot walking on continuous-nondifferentiable terrain by utilizing stability and interference criteria. Science China Technological Sciences, 2020, 63, 2527-2540.	4.0	18
7	Novel method for preventing shin-collisions in six-legged robots by utilising a robot–terrain interference model. Mechanism and Machine Theory, 2020, 151, 103897.	4. 5	20
8	Peg-in-Hole Assembly Based on Six-Legged Robots with Visual Detecting and Force Sensing. Sensors, 2020, 20, 2861.	3.8	7
9	Obstacle avoidance and motion planning scheme for a hexapod robot Octopus-III. Robotics and Autonomous Systems, 2018, 103, 199-212.	5.1	54
10	Obstacle avoidance for a hexapod robot in unknown environment. Science China Technological Sciences, 2017, 60, 818-831.	4.0	15