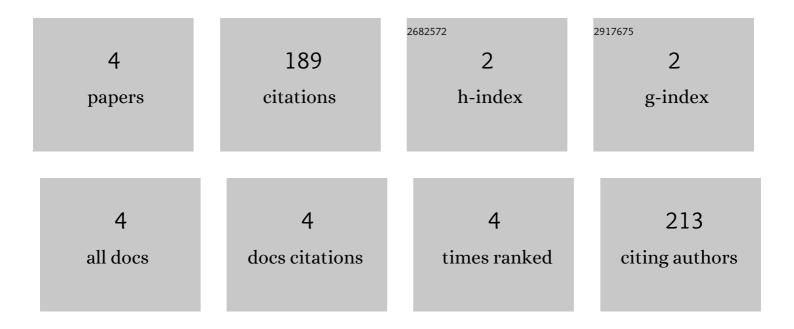
Francesco Forte

List of Publications by Year in descending order

Source: https://exaly.com/author-pdf/10381568/publications.pdf Version: 2024-02-01



#	Article	IF	CITATIONS
1	Developing an Aerial Manipulator Prototype: Physical Interaction with the Environment. IEEE Robotics and Automation Magazine, 2014, 21, 41-50.	2.0	129
2	Modeling and Control of a Class of Modular Aerial Robots Combining Under Actuated and Fully Actuated Behavior. IEEE Transactions on Control Systems Technology, 2015, 23, 1869-1885.	5.2	31
3	A class of modular aerial robots. , 2011, , .		18
4	Control of modular aerial robots: Combining under- and fully-actuated behaviors. , 2012, , .		11