Umashankar Nagarajan

List of Publications by Year in descending order

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1937685 2272923 11 404 4 4 citations g-index h-index papers 11 11 11 278 docs citations citing authors all docs times ranked

| # | Article | IF | CITATIONS |
|----|---|-----|-----------|
| 1 | The ballbot: An omnidirectional balancing mobile robot. International Journal of Robotics Research, 2014, 33, 917-930. | 8.5 | 90 |
| 2 | Trajectory planning and control of an underactuated dynamically stable single spherical wheeled mobile robot. , 2009, , . | | 77 |
| 3 | State transition, balancing, station keeping, and yaw control for a dynamically stable single spherical wheel mobile robot. , 2009, , . | | 75 |
| 4 | Integral admittance shaping: A unified framework for active exoskeleton control. Robotics and Autonomous Systems, 2016, 75, 310-324. | 5.1 | 71 |
| 5 | Planning in high-dimensional shape space for a single-wheeled balancing mobile robot with arms. , 2012, , . | | 17 |
| 6 | Shape space planner for shape-accelerated balancing mobile robots. International Journal of Robotics Research, 2013, 32, 1323-1341. | 8.5 | 16 |
| 7 | Generalized direction changing fall control of humanoid robots among multiple objects. , 2010, , . | | 14 |
| 8 | Integral Admittance Shaping for exoskeleton control. , 2015, , . | | 14 |
| 9 | Hybrid control for navigation of shape-accelerated underactuated balancing systems. , 2010, , . | | 11 |
| 10 | Integrated planning and control for graceful navigation of shape-accelerated underactuated balancing mobile robots. , 2012, , . | | 10 |
| 11 | Integrated motion planning and control for graceful balancing mobile robots. International Journal of Robotics Research, 2013, 32, 1005-1029. | 8.5 | 9 |