

Wenquan Gong

List of Publications by Year in descending order

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Version: 2024-02-01

12
papers

163
citations

1937685

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2272923

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12
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12
docs citations

12
times ranked

95
citing authors

#	ARTICLE	IF	CITATIONS
1	Fixed-time integral-type sliding mode control for the quadrotor UAV attitude stabilization under actuator failures. Aerospace Science and Technology, 2019, 95, 105444.	4.8	68
2	Appointed Fixed Time Observer-Based Sliding Mode Control for a Quadrotor UAV Under External Disturbances. IEEE Transactions on Aerospace and Electronic Systems, 2022, 58, 290-303.	4.7	59
3	Extended state observer-based finite-time dynamic surface control for trajectory tracking of a quadrotor unmanned aerial vehicle. Transactions of the Institute of Measurement and Control, 2020, 42, 2956-2968.	1.7	17
4	Nonsingular Terminal Sliding Mode Based Finite-Time Dynamic Surface Control for a Quadrotor UAV. Algorithms, 2021, 14, 315.	2.1	5
5	Integral-type Sliding Mode based Fault-tolerant Attitude Stabilization of A Quad-rotor UAV. , 2018, , .		4
6	Fixed-Time Attitude Tracking Control for Quadrotor UAVs Under Actuator Failures. , 2019, , .		3
7	Finite-time disturbance observer based attitude stabilization control under actuator failure. , 2018, , .		2
8	Appointed-finite-time Control for Quadrotor UAVs with External Disturbances: An Adaptive Sliding Mode Observer based Approach. , 2020, , .		2
9	Nonlinear Disturbance Observer based Dynamic Surface Control for Trajectory Tracking of a Quadrotor UAV. , 2018, , .		1
10	Fixed-time Trajectory Tracking Control of a Wheeled Mobile Robot. , 2021, , .		1
11	Finite-time Trajectory Tracking Control of A Wheel Mobile Robot based on Integral Terminal Sliding Mode. , 2020, , .		1
12	Observer based Appointed-finite-time Nonsingular Sliding Mode based Disturbance Attenuation Control for Quadrotor UAV. , 2020, , .		0