Junmin Wang

List of Publications by Citations

225 papers	6,750 citations	48 h-index	75 g-index
251 ext. papers	8,190 ext. citations	4 avg, IF	6.89 L-index

#	Paper	IF	Citations
225	Development and performance characterization of an electric ground vehicle with independently actuated in-wheel motors. *Journal of Power Sources*, **2011**, 196, 3962-3971	8.9	246
224	. *IEEE Transactions on Vehicular Technology*, **2014**, 63, 591-602	6.8	219
223	Vehicle Lateral Dynamics Control Through AFS/DYC and Robust Gain-Scheduling Approach. *IEEE Transactions on Vehicular Technology*, **2016**, 65, 489-494	6.8	211
222	Robust gain-scheduling energy-to-peak control of vehicle lateral dynamics stabilisation. *Vehicle System Dynamics*, **2014**, 52, 309-340	2.8	211
221	On Energy-to-Peak Filtering for Nonuniformly Sampled Nonlinear Systems: A Markovian Jump System Approach. *IEEE Transactions on Fuzzy Systems*, **2014**, 22, 212-222	8.3	192
220	Coordinated and Reconfigurable Vehicle Dynamics Control. *IEEE Transactions on Control Systems Technology*, **2009**, 17, 723-732	4.8	175
219	. *IEEE/ASME Transactions on Mechatronics*, **2016**, 21, 1659-1670	5.5	162
218	A Parallel Hybrid Electric Vehicle Energy Management Strategy Using Stochastic Model Predictive Control With Road Grade Preview. *IEEE Transactions on Control Systems Technology*, **2015**, 23, 2416-2423	4.8	152
217	Adaptive Sliding-Mode Observer Design for a Selective Catalytic Reduction System of Ground-Vehicle Diesel Engines. *IEEE/ASME Transactions on Mechatronics*, **2016**, 21, 2027-2038	5.5	151
216	Fault-Tolerant Control With Active Fault Diagnosis for Four-Wheel Independently Driven Electric Ground Vehicles. *IEEE Transactions on Vehicular Technology*, **2011**, 60, 4276-4287	6.8	145
215	Hybrid Electric Vehicle Model Predictive Control Torque-Split Strategy Incorporating Engine Transient Characteristics. *IEEE Transactions on Vehicular Technology*, **2012**, 61, 2458-2467	6.8	138
214	Lateral motion control for four-wheel-independent-drive electric vehicles using optimal torque allocation and dynamic message priority scheduling. *Control Engineering Practice*, **2014**, 24, 55-66	3.9	116
213	. *IEEE Transactions on Vehicular Technology*, **2011**, 60, 839-848	6.8	114
212	Linear Parameter-Varying Controller Design for Four-Wheel Independently Actuated Electric Ground Vehicles With Active Steering Systems. *IEEE Transactions on Control Systems Technology*, **2014**, 22, 1281-1296	4.8	113
211	State Estimation of Discrete-Time Takagi-Sugeno Fuzzy Systems in a Network Environment. *IEEE Transactions on Cybernetics*, **2015**, 45, 1525-36	10.2	106
210	Design and Evaluation on Electric Differentials for Overactuated Electric Ground Vehicles With Four Independent In-Wheel Motors. *IEEE Transactions on Vehicular Technology*, **2012**, 61, 1534-1542	6.8	101
209	Fast and Global Optimal Energy-Efficient Control Allocation With Applications to Over-Actuated Electric Ground Vehicles. *IEEE Transactions on Control Systems Technology*, **2012**, 20, 1202-1211	4.8	93

208	. *IEEE Transactions on Control Systems Technology*, **2008**, 16, 1138-1151	4.8	92
207	Design and Experimental Evaluations on Energy Efficient Control Allocation Methods for Overactuated Electric Vehicles: Longitudinal Motion Case. *IEEE/ASME Transactions on Mechatronics*, **2014**, 19, 538-548	5.5	91
206	Robust energy-to-peak sideslip angle estimation with applications to ground vehicles. *Mechatronics* , **2015**, 30, 338-347	3	90
205	. *IEEE Transactions on Industrial Electronics*, **2018**, 65, 7239-7247	8.9	88
204	Passive Actuator Fault-Tolerant Control for a Class of Overactuated Nonlinear Systems and Applications to Electric Vehicles. *IEEE Transactions on Vehicular Technology*, **2013**, 62, 972-985	6.8	86
203	Observer-based tracking controller design for networked predictive control systems with uncertain Markov delays. *International Journal of Control*, **2013**, 86, 1824-1836	1.5	86
202	Development and experimental studies of a control-oriented SCR model for a two-catalyst urea-SCR system. *Control Engineering Practice*, **2011**, 19, 409-422	3.9	85
201	Robust sliding-mode control for Markovian jump systems subject to intermittent observations and partially known transition probabilities. *Systems and Control Letters*, **2013**, 62, 1114-1124	2.4	82
200	Robust H ∞ sliding mode control with pole placement for a fluid power electrohydraulic actuator (EHA) system. *International Journal of Advanced Manufacturing Technology*, **2014**, 73, 1095-1104	3.2	79
199	Robust Weighted Gain-Scheduling $H_{infty }$ Vehicle Lateral Motion Control With Considerations of Steering System Backlash-Type Hysteresis. *IEEE Transactions on Control Systems Technology*, **2014**, 22, 1740-1753	4.8	78
198	Improving Vehicle Handling Stability Based on Combined AFS and DYC System via Robust Takagi-Sugeno Fuzzy Control. *IEEE Transactions on Intelligent Transportation Systems*, **2018**, 19, 2696-2707	6.1	77
197	Tire–road friction coefficient and tire cornering stiffness estimation based on longitudinal tire force difference generation. *Control Engineering Practice*, **2013**, 21, 65-75	3.9	75
196	Air fraction estimation for multiple combustion mode diesel engines with dual-loop EGR systems. *Control Engineering Practice*, **2008**, 16, 1479-1486	3.9	74
195	Adaptive Energy-Efficient Control Allocation for Planar Motion Control of Over-Actuated Electric Ground Vehicles. *IEEE Transactions on Control Systems Technology*, **2014**, 22, 1362-1373	4.8	70
194	Energy Management and Driving Strategy for In-Wheel Motor Electric Ground Vehicles With Terrain Profile Preview. *IEEE Transactions on Industrial Informatics*, **2014**, 10, 1938-1947	11.9	70
193	. *IEEE Transactions on Vehicular Technology*, **2016**, 1-1	6.8	70
192	A Two-Cell Backstepping-Based Control Strategy for Diesel Engine Selective Catalytic Reduction Systems. *IEEE Transactions on Control Systems Technology*, **2011**, 19, 1504-1515	4.8	68
191	. *IEEE Transactions on Control Systems Technology*, **2016**, 24, 1557-1572	4.8	60

190	. *IEEE Transactions on Intelligent Transportation Systems*, **2017**, 18, 1097-1108	6.1	59
189	Robust finite frequency H∞ static-output-feedback control with application to vibration active control of structural systems. *Mechatronics*, **2014**, 24, 354-366	3	57
188	Design and experimental validation of an extended Kalman filter-based NOx concentration estimator in selective catalytic reduction system applications. *Control Engineering Practice*, **2011**, 19, 346-353	3.9	57
187	Fault-Tolerant Control for Electric Ground Vehicles With Independently-Actuated In-Wheel Motors. *Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME*, **2012**, 134,	1.6	56
186	A robust wheel slip ratio control design combining hydraulic and regenerative braking systems for in-wheel-motors-driven electric Vehicles. *Journal of the Franklin Institute*, **2015**, 352, 577-602	4	54
185	. *IEEE Transactions on Vehicular Technology*, **2015**, 64, 4985-4995	6.8	53
184	A Driver Steering Model With Personalized Desired Path Generation. *IEEE Transactions on Systems, Man, and Cybernetics: Systems*, **2017**, 47, 111-120	7.3	52
183	Experimental investigation of diesel and biodiesel post injections during active diesel particulate filter regenerations. *Fuel*, **2014**, 130, 286-295	7.1	51
182	Control-oriented model for integrated diesel engine and aftertreatment systems thermal management. *Control Engineering Practice*, **2014**, 22, 81-93	3.9	51
181	Model predictive regenerative braking control for lightweight electric vehicles with in-wheel motors. *Proceedings of the Institution of Mechanical Engineers, Part D: Journal of Automobile Engineering*, **2012**, 226, 1220-1232	1.4	51
180	. *IEEE Transactions on Intelligent Transportation Systems*, **2017**, 18, 3049-3060	6.1	50
179	A Personalizable Driver Steering Model Capable of Predicting Driver Behaviors in Vehicle Collision Avoidance Maneuvers. *IEEE Transactions on Human-Machine Systems*, **2017**, 47, 625-635	4.1	50
178	Adaptive and Efficient Ammonia Storage Distribution Control for a Two-Catalyst Selective Catalytic Reduction System. *Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME*, **2012**, 134,	1.6	48
177	Air-fraction modeling for simultaneous Diesel engine NOx and PM emissions control during active DPF regenerations. *Applied Energy*, **2014**, 122, 310-320	10.7	47
176	Robust speed synchronization control for clutchless automated manual transmission systems in electric vehicles. *Proceedings of the Institution of Mechanical Engineers, Part D: Journal of Automobile Engineering*, **2015**, 229, 424-436	1.4	45
175	NO and NO2 Concentration Modeling and Observer-Based Estimation Across a Diesel Engine Aftertreatment System. *Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME*, **2011**, 133,	1.6	42
174	Robust lateral motion control of four-wheel independently actuated electric vehicles with tire force saturation consideration. *Journal of the Franklin Institute*, **2015**, 352, 645-668	4	41
173	Combined feedback–feedforward tracking control for networked control systems with probabilistic delays. *Journal of the Franklin Institute*, **2014**, 351, 3477-3489	4	39

172	A feedforward and feedback integrated lateral and longitudinal driver model for personalized advanced driver assistance systems. *Mechatronics*, **2018**, 50, 177-188	3	37
171	. *IEEE Transactions on Vehicular Technology*, **2016**, 65, 3874-3887	6.8	37
170	Control of diesel engine dual-loop EGR air-path systems by a singular perturbation method. *Control Engineering Practice*, **2013**, 21, 981-988	3.9	37
169	. *IEEE Transactions on Transportation Electrification*, **2016**, 2, 200-209	7.6	36
168	Observer-Based Estimation of Air-Fractions for a Diesel Engine Coupled With Aftertreatment Systems. *IEEE Transactions on Control Systems Technology*, **2013**, 21, 2239-2250	4.8	36
167	Robust control for four wheel independently-actuated electric ground vehicles by external yaw-moment generation. *International Journal of Automotive Technology*, **2015**, 16, 839-847	1.6	34
166	Autonomous ground vehicle control system for high-speed and safe operation. *International Journal of Vehicle Autonomous Systems*, **2009**, 7, 18	0.4	34
165	Robust H□dynamic output-feedback control for four-wheel independently actuated electric ground vehicles through integrated AFS/DYC. *Journal of the Franklin Institute*, **2018**, 355, 9321-9350	4	33
164	A Stochastic Driver Pedal Behavior Model Incorporating Road Information. *IEEE Transactions on Human-Machine Systems*, **2017**, 47, 614-624	4.1	32
163	Nonlinear Observer Design of Diesel Engine Selective Catalytic Reduction Systems With $hbox{NO}_{x}$ Sensor Measurements. *IEEE/ASME Transactions on Mechatronics*, **2015**, 20, 1585-1594	5.5	32
162	Lightweight Vehicle Control-Oriented Modeling and Payload Parameter Sensitivity Analysis. *IEEE Transactions on Vehicular Technology*, **2011**, 60, 1999-2011	6.8	32
161	Cycle-based optimal NOx emission control of selective catalytic reduction systems with dynamic programming algorithm. *Fuel*, **2015**, 141, 200-206	7.1	30
160	Human-Centered Trajectory Tracking Control for Autonomous Vehicles With Driver Cut-In Behavior Prediction. *IEEE Transactions on Vehicular Technology*, **2019**, 68, 8461-8471	6.8	29
159	. *IEEE Transactions on Vehicular Technology*, **2016**, 65, 4740-4751	6.8	29
158	A two-level stochastic approach to optimize the energy management strategy for fixed-route hybrid electric vehicles. *Mechatronics*, **2016**, 38, 93-102	3	29
157	Estimation and adaptive nonlinear model predictive control of selective catalytic reduction systems in automotive applications. *Journal of Process Control*, **2016**, 40, 78-92	3.9	29
156	. *IEEE Transactions on Vehicular Technology*, **2014**, 63, 4221-4231	6.8	29
155	. *IEEE Transactions on Vehicular Technology*, **2016**, 1-1	6.8	29

154	Driver-Assistance Lateral Motion Control for In-Wheel-Motor-Driven Electric Ground Vehicles Subject to Small Torque Variation. *IEEE Transactions on Vehicular Technology*, **2018**, 67, 6838-6850	6.8	26
153	. *IEEE Transactions on Intelligent Transportation Systems*, **2014**, 15, 239-249	6.1	26
152	Robust Filtering for Ammonia Coverage Estimation in Diesel Engine Selective Catalytic Reduction Systems. *Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME*, **2013**, 135,	1.6	26
151	Two-Level Nonlinear Model Predictive Control for Lean NOx Trap Regenerations. *Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME*, **2010**, 132,	1.6	26
150	Ultra-local model predictive control: A model-free approach and its application on automated vehicle trajectory tracking. *Control Engineering Practice*, **2020**, 101, 104482	3.9	25
149	Center of gravity height real-time estimation for lightweight vehicles using tire instant effective radius. *Control Engineering Practice*, **2013**, 21, 370-380	3.9	25
148	Robust two-mode-dependent controller design for networked control systems with random delays modelled by Markov chains. *International Journal of Control*, **2015**, 88, 2499-2509	1.5	24
147	Ammonia coverage ratio and input simultaneous estimation in ground vehicle selective catalytic reduction (SCR) systems. *Journal of the Franklin Institute*, **2015**, 352, 708-723	4	24
146	Output-feedback robust control for vehicle path tracking considering different human drivers characteristics. *Mechatronics*, **2018**, 50, 402-412	3	24
145	. *IEEE Transactions on Vehicular Technology*, **2016**, 65, 1199-1211	6.8	24
144	Multiobjective Optimization of Lane-Changing Strategy for Intelligent Vehicles in Complex Driving Environments. *IEEE Transactions on Vehicular Technology*, **2020**, 69, 1291-1308	6.8	24
143	Globally energy-optimal speed planning for road vehicles on a given route. *Transportation Research Part C: Emerging Technologies*, **2018**, 93, 148-160	8.4	23
142	Development and experimental validation of a control-oriented Diesel engine model for fuel consumption and brake torque predictions. *Mathematical and Computer Modelling of Dynamical Systems*, **2011**, 17, 261-277	1	22
141	On the Control Allocation for Coordinated Ground Vehicle Dynamics Control Systems. *Proceedings of the American Control Conference*, **2007**,	1.2	22
140	Removal of NOx sensor ammonia cross sensitivity from contaminated measurements in Diesel-engine selective catalytic reduction systems. *Fuel*, **2015**, 150, 448-456	7.1	21
139	. *IEEE Transactions on Vehicular Technology*, **2019**, 68, 4527-4536	6.8	20
138	. *IEEE/ASME Transactions on Mechatronics*, **2019**, 24, 2779-2790	5.5	20
137	Fuzzy Observer-Based Transitional Path-Tracking Control for Autonomous Vehicles. *IEEE Transactions on Intelligent Transportation Systems*, **2021**, 22, 3078-3088	6.1	20

136	Rollover speed prediction on curves for heavy vehicles using mobile smartphone. *Measurement: Journal of the International Measurement Confederation*, **2018**, 130, 404-411	4.6	19
135	A physics-based time-varying transport delay oxygen concentration model for dual-loop exhaust gas recirculation (EGR) engine air-paths. *Applied Energy*, **2014**, 125, 300-307	10.7	19
134	Nonlinear and adaptive control of NO/NO2 ratio for improving selective catalytic reduction system performance. *Journal of the Franklin Institute*, **2013**, 350, 1992-2012	4	19
133	Linear parameter-varying-based fault-tolerant controller design for a class of over-actuated non-linear systems with applications to electric vehicles. *IET Control Theory and Applications*, **2014**, 8, 705-717	2.5	19
132	. *IEEE Transactions on Vehicular Technology*, **2017**, 66, 10935-10945	6.8	18
131	Velocity Optimization for Braking Energy Management of In-Wheel Motor Electric Vehicles. *IEEE Access*, **2019**, 7, 66410-66422	3.5	18
130	Motor/Generator Applications in Electrified Vehicle Chassis□A Survey. *IEEE Transactions on Transportation Electrification*, **2019**, 5, 584-601	7.6	18
129	. *IEEE/ASME Transactions on Mechatronics*, **2017**, 22, 1195-1206	5.5	18
128	Motion Planning With Velocity Prediction and Composite Nonlinear Feedback Tracking Control for Lane-Change Strategy of Autonomous Vehicles. *IEEE Transactions on Intelligent Vehicles*, **2020**, 5, 63-74	5	17
127	. *IEEE/ASME Transactions on Mechatronics*, **2015**, 20, 2222-2233	5.5	16
126	Nonlinear Model Predictive Control of Integrated Diesel Engine and Selective Catalytic Reduction System for Simultaneous Fuel Economy Improvement and Emissions Reduction. *Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME*, **2015**, 137,	1.6	16
125	Introducing mass parameters to Pseudo□Rigid□Body models for precisely predicting dynamics of compliant mechanisms. *Mechanism and Machine Theory*, **2018**, 126, 273-294	4	15
124	Pressure-based transient intake manifold temperature reconstruction in Diesel engines. *Control Engineering Practice*, **2012**, 20, 531-538	3.9	15
123	Vehicle Path-Tracking Linear-Time-Varying Model Predictive Control Controller Parameter Selection Considering Central Process Unit Computational Load. *Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME*, **2019**, 141,	1.6	15
122	NOx Sensor Ammonia-Cross-Sensitivity Factor Estimation in Diesel Engine Selective Catalytic Reduction Systems. *Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME* , **2015**, 137,	1.6	14
121	Longitudinal Motion Based Lightweight Vehicle Payload Parameter Real-Time Estimations. *Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME*, **2013**, 135,	1.6	14
120	Oxygen Concentration Dynamic Model and Observer-Based Estimation Through a Diesel Engine Aftertreatment System. *Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME*, **2012**, 134,	1.6	14
119	Optimizing the Energy Management Strategy for Plug-In Hybrid Electric Vehicles With Multiple Frequent Routes. *IEEE Transactions on Control Systems Technology*, **2019**, 27, 394-400	4.8	14

118	Design and Modeling of a Compliant Link for Inherently Safe Corobots. *Journal of Mechanisms and Robotics*, **2018**, 10,	2.2	14
117	Robust Vehicle Driver Assistance Control for Handover Scenarios Considering Driving Performances. *IEEE Transactions on Systems, Man, and Cybernetics: Systems*, **2021**, 51, 4160-4170	7.3	13
116	Correction of contaminated yaw rate signal and estimation of sensor bias for an electric vehicle under normal driving conditions. *Mechanical Systems and Signal Processing*, **2017**, 87, 64-80	7.8	12
115	Stable and Optimal Load Sharing of Multiple PMSGs in an Islanded DC Microgrid. *IEEE Transactions on Energy Conversion*, **2018**, 33, 260-271	5.4	11
114	Control-Oriented Modeling and Observer-Based Estimation of Solid and Gas Temperatures for a Diesel Engine Aftertreatment System. *Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME*, **2012**, 134,	1.6	11
113	In-Wheel-Motor-Driven Electric Vehicles Motion Control Methods Considering Motor Thermal Protection. *Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME*, **2019**, 141,	1.6	11
112	An adaptive energy-efficient control allocation on planar motion control of electric ground vehicles **2011**,		10
111	Adaptive Observer for Joint Estimation of Oxygen Fractions and Blend Level in Biodiesel Fueled Engines. *IEEE Transactions on Control Systems Technology*, **2015**, 23, 80-90	4.8	9
110	Modeling and control of inherently safe robots with variable stiffness links. *Robotics and Autonomous Systems*, **2019**, 120, 103247	3.5	9
109	Control-oriented multi-phase combustion model for biodiesel fueled engines. *Applied Energy*, **2013**, 108, 92-99	10.7	9
108	A novel cost-effective robust approach for selective catalytic reduction state estimations using dual nitrogen oxide sensors. *Proceedings of the Institution of Mechanical Engineers, Part D: Journal of Automobile Engineering*, **2015**, 229, 83-96	1.4	9
107	Optimization of the ammonia coverage ratio references in diesel engine two-can selective catalytic reduction systems via nonlinear model predictive control. *Proceedings of the Institution of Mechanical Engineers, Part D: Journal of Automobile Engineering*, **2014**, 228, 1452-1467	1.4	9
106	Energy-efficient control allocation with applications on planar motion control of electric ground vehicles **2011**,		9
105	Nonlinear observer designs for diesel engine selective catalytic reduction (SCR) ammonia coverage ratio estimation **2009**,		9
104	Simultaneous Estimation of Vehicle Center of Gravity and Inertial Parameters Based on Ackermann Steering Geometry. *Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME*, **2017**, 139,	1.6	8
103	Analysis of Human Driver Behavior in Highway Cut-in Scenarios **2017**,		8
102	. *IEEE/ASME Transactions on Mechatronics*, **2018**, 23, 190-199	5.5	8
101	Hand-wheel steering signal estimation and diagnosis approaches for ground vehicles. *Control Engineering Practice*, **2012**, 20, 654-662	3.9	8

100	Coordinated Active Thermal Management and Selective Catalytic Reduction Control for Simultaneous Fuel Economy Improvement and Emissions Reduction During Low-Temperature Operations. *Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME*, **2015**, 137,	1.6	8
99	Obstacle Detection for Autonomous Driving Vehicles With Multi-LiDAR Sensor Fusion. *Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME*, **2020**, 142,	1.6	8
98	Observer-Based Estimation of Aging Condition for Selective Catalytic Reduction Systems in Vehicle Applications. *Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME*, **2017** , 139,	1.6	7
97	Cycle-based ammonia-coverage-ratio reference generator design for Diesel engine two-cell selective catalytic reduction systems via a fuzzy approach. *Fuel*, **2015**, 159, 76-83	7.1	7
96	Autonomous Vehicle Trajectory Following: A Flatness Model Predictive Control Approach With Hardware-in-the-Loop Verification. *IEEE Transactions on Intelligent Transportation Systems*, **2020**, 1-11	6.1	7
95	Adaptive vehicle planar motion control with fast parameter estimation **2012**,		7
94	Nonlinear model predictive control of lean NOx trap regenerations **2009**,		7
93	. *IEEE Transactions on Intelligent Transportation Systems*, **2021**, 1-11	6.1	7
92	Human-centered feed-forward control of a vehicle steering system based on a driver's steering model **2015**,		6
91	Robust vehicle longitudinal motion control subject to in-wheel-motor driving torque variations **2017**,		6
90	Application of NMPC on optimization of ammonia coverage ratio references in two-can diesel SCR systems **2014**,		6
89	Design and Robustness Analysis of Discrete Observers for Diesel Engine In-Cylinder Oxygen Mass Fraction Cycle-by-Cycle Estimation. *IEEE Transactions on Control Systems Technology*, **2011**,	4.8	6
88	An extended Kalman filter for NOx sensor ammonia cross-sensitivity elimination in selective catalytic reduction applications **2010**,		6
87	An extended Kalman filter for ammonia coverage ratio and capacity estimations in the application of Diesel engine SCR control and onboard diagnosis **2010**,		6
86	Impaired Driver Assistance Control With Gain-Scheduling Composite Nonlinear Feedback for Vehicle Trajectory Tracking. *Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME*, **2020**, 142,	1.6	6
85	Toward Tradeoff Between Impact Force Reduction and Maximum Safe Speed: Dynamic Parameter Optimization of Variable Stiffness Robots. *Journal of Mechanisms and Robotics*, **2020**, 12,	2.2	6
84	Predictive energy management strategy for electric vehicles based on estimation of preceding vehicle future movements **2016**,		6
83	Self-Adaptive Equivalent Consumption Minimization Strategy for Hybrid Electric Vehicles. *IEEE Transactions on Vehicular Technology*, **2021**, 70, 189-202	6.8	6

82	A robust ammonia coverage ratio control method for a two-cell selective catalytic reduction system in low temperature operations **2014**,		5
81	A robust wheel slip control design for in-wheel-motor-driven electric vehicles with hydraulic and regenerative braking systems **2014**,		5
80	Robust fuzzy control for vehicle lateral dynamic stability via Takagi-Sugeno fuzzy approach **2017**,		5
79	Sliding-mode observers for urea selective catalytic reduction system state estimations based on nitrogen oxide sensor measurements. *Proceedings of the Institution of Mechanical Engineers, Part D: Journal of Automobile Engineering*, **2015**, 229, 835-849	1.4	5
78	Stochastic optimal control for hybrid electric vehicles running on fixed routes **2015**,		5
77	Nonlinear model predictive control for improving energy recovery for electric vehicles during regenerative braking **2011**,		5
76	MC-Safe. *ACM Transactions on Cyber-Physical Systems*, **2020**, 4, 1-27	2.3	5
75	Traffic signal timing optimization incorporating individual vehicle fuel consumption characteristics under connected vehicles environment **2016**,		5
74	A Personalized Human-Like Lane-Changing Trajectory Planning Method for Automated Driving System. *IEEE Transactions on Vehicular Technology*, **2021**, 70, 6399-6414	6.8	5
73	Fault-type identification and fault estimation of the active steering system of an electric vehicle in normal driving conditions. *Proceedings of the Institution of Mechanical Engineers, Part D: Journal of Automobile Engineering*, **2017**, 231, 1679-1692	1.4	4
72	Control of aged automotive selective catalytic reduction systems for consistent performances. *Journal of the Franklin Institute*, **2017**, 354, 8094-8116	4	4
71	Robust Gain-Scheduling Control of Vehicle Lateral Dynamics Through AFS/DYC **2018**, 339-368		4
70	Energetic Impacts Evaluation of Eco-Driving on Mixed Traffic With Driver Behavioral Diversity. *IEEE Transactions on Intelligent Transportation Systems*, **2020**, 1-12	6.1	4
69	Popov-HJRobust Path-Tracking Control of Autonomous Ground Vehicles with Consideration of Sector Bounded Kinematic Nonlinearity. *Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME*, **2021**,	1.6	4
68	Comparative Study and Accommodation of Biodiesel in Diesel-Electric Hybrid Vehicles Coupled with Aftertreatment Systems. *Asian Journal of Control*, **2016**, 18, 3-15	1.7	4
67	Trajectory Tracking Control for Autonomous Vehicles in Different Cut-in Scenarios **2019**,		4
66	Flatness-based Model Predictive Control for Autonomous Vehicle Trajectory Tracking **2019**,		4
65	Personalized Vehicle Path Following Based on Robust Gain-scheduling Control in Lane-changing and Left-turning Maneuvers **2018**,		4

64	. *IEEE Transactions on Vehicular Technology*, **2019**, 68, 6429-6440	6.8	3
63	NO$_x$ Sensor Reading Correction in Diesel Engine Selective Catalytic Reduction System Applications. *IEEE/ASME Transactions on Mechatronics*, **2015**, 1-1	5.5	3
62	A least-squares regression based method for vehicle yaw moment of inertia estimation **2015**,		3
61	Sliding-mode Control of Ammonia Coverage Ratio for Automotive Selective Catalytic Reduction Systems **2018**,		3
60	Predictive energy management strategy for fully electric vehicles based on hybrid model predictive control **2017**,		3
59	Sensitivity analysis of human driving characteristics on road and driving conditions for active vehicle control systems **2014**,		3
58	Control-oriented modeling of thermal behaviors for a Diesel oxidation catalyst **2012**,		3
57	Observer Based Oxygen Fraction Estimation for a Dual-Loop EGR Diesel Engine Fueled With Biodiesel Blends **2013**,		3
56	Stability control of electric vehicles with four independently actuated wheels **2011**,		3
55	Vehicle yaw inertia and mass independent adaptive control for stability and trajectory tracking enhancements **2009**,		3
54	A Comparative Study on the Effect of Mechanical Compliance for a Safe Physical Human-Robot Interaction. *Journal of Mechanical Design, Transactions of the ASME*, **2020**, 142,	3	3
53	A Novel Vehicle Tracking Method for Cross-Area Sensor Fusion with Reinforcement Learning Based GMM **2020**,		3
52	WiDrive: Adaptive WiFi-Based Recognition of Driver Activity for Real-Time and Safe Takeover **2019**,		3
51	Sliding-mode control of automotive selective catalytic reduction systems with state estimation. *Proceedings of the Institution of Mechanical Engineers, Part D: Journal of Automobile Engineering*, **2020**, 234, 630-644	1.4	3
50	Tutorial of model-based powertrain and aftertreatment system control design and implementation **2015**,		2
49	Load-dependent observer design for active suspension systems. *International Journal of Vehicle Design*, **2015**, 68, 162	2.4	2
48	State estimation for a four-wheel-independent-drive electric ground vehicle **2015**,		2
47	Advanced Control and Optimization with Applications to Complex Automotive Systems. *Mathematical Problems in Engineering*, **2014**, 2014, 1-3	1.1	2

46	A Stochastic Model Predictive Control Approach for Hybrid Electric Vehicle Energy Management With Road Grade Preview **2014**,		2
45	Integrated diesel engine and selective catalytic reduction system active NOx control for fuel economy improvement **2013**,		2
44	Oxygen Concentration Dynamic Model Through a Diesel Engine Aftertreatment System **2011**,		2
43	Input constrained non-equilibrium transient trajectory shaping control for a class of nonlinear systems **2010**,		2
42	Vehicle-longitudinal-motion-independent real-time tire-road friction coefficient estimation **2010**,		2
41	Non-equilibrium transient trajectory shaping control via a three-stage switching method for a class of nonlinear systems **2010**,		2
40	Incremental Model Predictive Control of Active Suspensions With Estimated Road Preview Information From a Lead Vehicle. *Journal of Dynamic Systems, Measurement and Control, Transactions of the ASME*, **2020**, 142,	1.6	2
39	Personalized Ground Vehicle Collision Avoidance System: From a Computational Resource Re-allocation Perspective **2020**,		2
38	Design, Modeling, and Manufacturing of a Variable Lateral Stiffness Arm Via Shape Morphing Mechanisms. *Journal of Mechanisms and Robotics*, **2021**, 13,	2.2	2
37	Parameter Selection of an LTV-MPC Controller for Vehicle Path Tracking Considering CPU Computational Load **2018**,		2
36	A Study on Economical Vehicle Platooning Strategy in Urban Driving Scenarios **2018**,		2
35	Dynamic Channel Selection for Real-Time Safety Message Communication in Vehicular Networks **2018**,		2
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