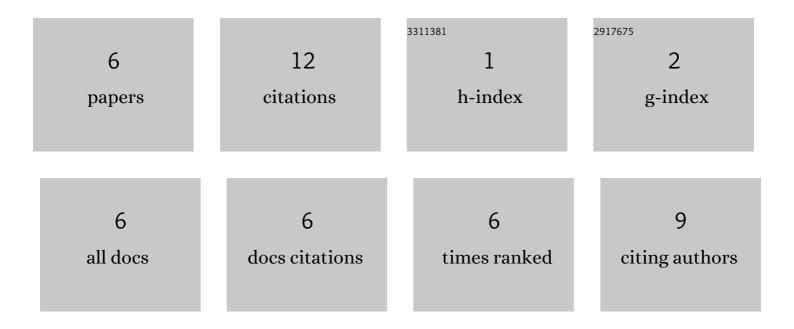
Suyong Kim

List of Publications by Year in descending order

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SUVONC KIM

#	Article	IF	CITATIONS
1	A 3-DOF sensor to estimate the force applied to the tip of a surgical instrument. , 2017, , .		8
2	Control of Haptic Systems Based on Input-to-State Stability. IEEE Access, 2022, 10, 27242-27254.	4.2	2
3	A method to estimate the axial force applied to a surgical instrument tip considering the effect of the gravity. , 2017, , .		1
4	Estimation of Vertical Interaction Force to the End of a Surgical Instrument by Measuring Reaction Force to the Trocar Support. Journal of Institute of Control, Robotics and Systems, 2016, 22, 615-618.	0.2	1
5	Improved estimation of torque between a surgical instrument and environment in multi-DOF motion. Journal of Mechanical Science and Technology, 2018, 32, 2817-2828.	1.5	Ο
6	Method to Estimate the Axial Force Applied to an Instrument Tip in Consideration of Friction Occurring on a Rubber Packing Inside a Trocar. Journal of Institute of Control, Robotics and Systems, 2018, 24, 271-277.	0.2	0